Numerical schemes for degenerate boundary value problems

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## LETTER TO THE EDITOR

# Numerical schemes for degenerate boundary value problems 

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#### Abstract

Methods for accurately determining solutions of degenerate boundary value problems are described. Nonlinear problems are first approximated by sequences of linear problems. A finite difference procedure which incorporates the effect of the degeneracy in the matrix of the linear discretized system of equations is developed. The simple tridiagonal structure of the matrix allows fast, accurate calculations to be performed with quite modest computer support. The results are readily improved using Richardson extrapolation.


Various physically important phenomena have been described using differential equations which degenerate at the boundary. These equations may be linear or nonlinear, and their solution causes numerical difficulties due to at least one of the derivatives of the solution becoming infinite at a boundary value [9]. In the case of nonlinear problems a quasilinearizaton technique [3] is often applicable, producing a sequence of degenerate linear differential equations converging to a solution of the nonlinear problem [15, 16]. However, approximation of a degenerate problem using a standard finite difference scheme is rarely satisfactory, particularly near the source of the degeneracy. Our aim is to illustrate how a new discretization technique can be used to provide accurate solutions simply and rather efficiently.

In many physical systems described by partial differential equations involving the Laplacian and the Dirichlet boundary conditions, the property of radial symmetry allows a reduction to a differential equation with one independent space variable (ordinary differential equation) or a partial differential equation in exactly two (one space, one time) variables. The dependency of the solution $u$ on the 'radial' space variable $r$ will then involve terms of the form $u^{\prime \prime}+(b / r) u^{\prime}$. This is the case for nonlinear reaction-diffusion equations [10] where radially symmetric solutions play a useful role. The cubic Schrödinger equation in ( $n+1$ )-dimensional spacetime reduces to a form containing the space derivatives $u^{\prime \prime}+((n-1) / r) u^{\prime}$. Particular cases arise in nonlinear optics, where $n=2$ and $u$ is the envelope of an electromagnetic wave [12], and plasma physics, where $n=3$ and $u$ is the envelope of a Langmuir wave [11]. There are physical applications for non-integral values of $b$ also. In the theory of generalized axially symmetric heat potentials, values of $b$ in the interval [ 0,2 ] arise when describing the conduction of heat in bodies of various shapes [1,19]. Finally, even when a problem is not inherently symmetrical, radially symmetric solutions may be a launchpad for a perturbation analysis [18].

However, one major problem associated with the reduction process we have described arises when a boundary condition at $r=0$ is present. The differential form $u^{\prime \prime}+(b / r) u^{\prime}$ will have an unwelcome singularity when $b \neq 0$, and degeneracy is said to occur at $r=0$.

To analyse this situation further, we consider the ordinary differential equation $u^{\prime \prime}+(b / r) u^{\prime}+f(r) g(u)=0$, where $f$ and $g$ are continuous functions. This is equivalent to the equation

$$
\begin{equation*}
\left(r^{b} u^{\prime}\right)^{\prime}+r^{b} f(r) g(u)=0 \tag{1}
\end{equation*}
$$

When $f(r)=r^{a}$ and $g(u)=u^{c}$, with $a, b, c$ real numbers and $c>0,(1)$ is the EmdenFowler equation. For $a=0, b=2, c=n$, typically 1.5 or $2.5,(1)$ is of importance in gas dynamics [5,6]. There are more recent applications in fluid mechanics, relativistic mechanics, nuclear physics and chemically reacting systems and excellent bibliographies have been published [13,21]. Equation (1) can be further reduced to the form $y^{\prime \prime}(x)+h(x, y(x))=0$ by a Liouville transformation. When $f, g$ are power functions, then $h$ is a product of powers of $x$ and $y$. Consequently, there are many physical phenomena whose behaviour can be related to the solution $y$ of the nonlinear equation $y^{\prime \prime}(x)=c x^{p} y^{q}(x),(c=$ constant $)$.

For illustration, we apply the numerical procedure to the degenerate two point boundary value problem [7]:

$$
\begin{equation*}
y^{\prime \prime}(x)=x^{p} y^{q}(x) \tag{2}
\end{equation*}
$$

with $-2<p<0, q>1$, and $y(0)=1, y(a)=0$. The particular case $p=-\frac{1}{2}, q=\frac{3}{2}$ arises in the case of an ionized atom in Thomas-Fermi theory [8,20].

We specify the nature of a degeneracy by means of the limit

$$
\lim _{x \rightarrow p}\left\{y^{R}(x)(x-p)^{P}\right\}=k
$$

where $y^{r}$ is the $r$ th derivative of any solution, $p$ is a boundary point, $k$ is a real constant, $R=\min \left\{r: y^{r}(a)\right.$ is infinite $\}$, and $P$ is the smallest positive rational number for which the limit is finite. The degeneracy is said to be of order $(R, P)$ at $x=p$ or the differential equation to be (degenerate) of class $D_{P}^{R}$ at $x=p$. The problem (2) will be approximated by sequences of linear two point boundary value problems each being discretized to form a tridiagonal matrix system. Accurate numerical solutions can be obtained when the equation is of class $D_{P}^{2}$, with $0<P<1$ at $x=0$. If $p<-1$, the problem is of class $D_{-1-p}^{1}$ and the solution of the discretized equations will not represent the solution of the nonlinear problem as accurately in this case.

The first step is to obtain algorithms for the sequence of linear boundary value problems which can be used to approximate the problem. The problem (2) is transformed to the form

$$
\begin{align*}
& -\ddot{u}(t)+a^{2+p} q t^{p} u(t)=a^{2+p} t^{p}[(1-t)-u(t)]^{q}+a^{2+p} q t^{p} u(t)  \tag{3}\\
& u(0)=u(1)=0
\end{align*}
$$

which is a generalization of the form (5.2) in [15], possessing homogeneous boundary conditions, and a solution $u(t)$ satisfying $u(t)=(1-t)-y(t a)=(1-x / a)-y(x)$, for $x$ in $[0, a]$.

Generalizing on the method for developing the algorithm (3.3) in [15], we obtain

$$
\begin{align*}
& -u_{n+1}^{\prime \prime}(t)+a^{2+p} q t^{p} u_{n+1}(t)=a^{2+p} t^{p}\left[(1-t)-u_{n}(t)\right]^{q}+a^{2+p} q t^{p} u_{n}(t)  \tag{4}\\
& u_{n+1}(0)=u_{n+1}(1)=0
\end{align*}
$$

converging monotonically upwards from $u_{0}(t)=0$ and downwards from $u_{0}(t)=1-t$ to the solution of the transformed general Emden problem (3).

Putting $u_{i}(t)=(1-t)-w_{t}(t)$ in (4) above gives

$$
\begin{align*}
& w_{n+1}^{\prime \prime}(t)-a^{2+p} q t^{p} w_{n+1}(t)=a^{2+p} t^{p}\left\{\left[w_{n}(t)\right]^{q}-q w_{n}(t)\right\} \\
& w_{n+1}(0)=1 \quad w_{n+1}(1)=0 \tag{5}
\end{align*}
$$

with $w(t)=y(t a)=y(x)$, and $w_{n}(t)$ converging to the solution of the problem

$$
\begin{align*}
& w^{\prime \prime}(t)=a^{2+p} t^{p} w^{q}(t)  \tag{6}\\
& w(0)=1 \quad w(1)=0
\end{align*}
$$

This algorithmic scheme has linear or first-order convergence. A faster, one-sided scheme, may be obtained by quasilinearization. Thus, for a particular problem, this approach is capable of providing several numerical schemes whose results can be compared. Generalizing on the algorithm (3.4) in [15], we can obtain the second-order scheme
$-v_{n+1}^{\prime \prime}(t)=a^{2+p_{t}}{ }^{p}\left[(1-t)-v_{n}(t)\right]^{q}-a^{2+p} q t^{p}\left[(1-t)-v_{n}(t)\right]^{q-1}\left\{v_{n+1}(t)-v_{n}(t)\right\}$
$v_{n+1}(0)=v_{n+1}(1)=0$
which converges monotonically upwards from $v_{0}(t)=0$ to the solution of the transformed Emden problem (3) above, on the interval $[0,1)$.

Now putting $v_{1}(t)=(1-t)-w_{i}(t)$ in (7) gives

$$
\begin{align*}
& w_{n+1}^{\prime \prime}(t)-a^{2+p} q t^{p}\left[w_{n}(t)\right]^{q-1} w_{n+1}(t)=a^{2+p} t^{p}\left\{\left[w_{n}(t)\right]^{q}-q\left[w_{n}(t)\right]^{q}\right\}  \tag{8}\\
& w_{n+1}(0)=1 \quad w_{n+1}(1)=0
\end{align*}
$$

converging monotonically downwards from $u_{0}(t)=1-t$ to the solution of problem (6). Taking $a=1$, and therefore $t=x, w(t)=y(x)$ in the problem (6) and the approximating sequences (5) and (8), gives the respective sequences

$$
\begin{align*}
& y_{n+1}^{\prime \prime}(x)-q x^{p} y_{n+1}(x)=x^{p}\left\{\left[y_{n}(x)\right]^{q}-q y_{n}(x)\right\} \\
& y_{n+1}(0)=1 \quad y_{n+1}(1)=0 \tag{9}
\end{align*}
$$

and

$$
\begin{align*}
& y_{n+1}^{\prime \prime}(x)-q x^{p}\left[y_{n}(x)\right]^{q-1} y_{n+1}(x)=(1-q) x^{p}\left[y_{n}(x)\right]^{q}  \tag{10}\\
& y_{n+1}(0)=1 \quad y_{n+1}(1)=0
\end{align*}
$$

converging to the solution of the generalized Emden problem

$$
\begin{align*}
& y^{\prime \prime}(x)=x^{p} y^{q}(x) \quad 0<x<1  \tag{11}\\
& y(0)=1 \quad y(1)=0 .
\end{align*}
$$

The next step is to discretize these sequences effectively. Choosing a uniform grid:

$$
0=x_{0}<x_{1}<\ldots<x_{N-1}<X_{N}=1
$$

with $h=1 / N, x_{r}=r h, r=1(1) N$ then, for $x=x_{r}, 1 \leqslant r \leqslant N-1$, we have for any iterative solution $y$ :

$$
\begin{aligned}
& y(x+h)-2 y(x)+y(x-h) \\
& \quad=h^{2} y^{(2)}(x)+2 h^{4} y^{(4)}(x) / 4!+2 h^{6} y^{(6)}(x) / 6!+\cdots .
\end{aligned}
$$

Using (9) with $y^{(2)}(x)$ in place of $y_{n+1}^{\prime \prime}(x)$, then $y^{(2)}$ is expressible in terms of $y(x)$ and the previous iterate $y_{n}(x)$. For instance, for the first iterate in (9) with $y_{0}(x)=0$, we have

$$
y_{r+1}-\left(2+q h^{2+p} r^{p}\right) y_{r}+y_{r-1}=2 h^{4} y_{r}^{(4)} / 4!+2 h^{6} y_{r}^{(6)} / 6!+\cdots
$$

where $y_{r}=y\left(x_{r}\right)=y(r h)$, for $1 \leqslant r \leqslant N-1$. However, since the derivatives contain negative powers of $x$ that are large for values of $x=r h$ close to zero, the accuracy can be seen to be at best $O\left(h^{2+p}\right)$. At least $O\left(h^{2}\right)$ accuracy is required for the effective use of the 'deferred approach to the limit' technique on the resulting discretization schemes. To accomplish this, all $h^{2+p}$ terms are collected on the left-hand side giving, after a little algebra for series, the first lower iterate in (9):

$$
\begin{equation*}
y_{r+1}-\left(2+q h^{2+p_{r} p} \sum \alpha_{r, m}\right) y_{r}+y_{r-1}=O\left(h^{3+p}\right) \quad(1 \leqslant r \leqslant N-1) \tag{12}
\end{equation*}
$$

where $\sum \alpha_{r, m}=r^{2}\left[(1+1 / r)^{p+2}+(1-1 / r)^{p+2}-2\right] /(p+1)(p+2)(p>-1)$. The sum is the addition of all coefficients of terms in $h^{2+p}$. For subsequent (all) iterates, the general expression is
$y_{r+1}-\left(2+q v_{r}(h)\right) y_{r}+y_{r-1}=v_{r}(h) f_{r}+O\left(h^{3+p}\right) \quad(1 \leqslant r \leqslant N-1)$,
where $v_{r}(h)=h^{2+p_{r} p} \sum \alpha_{r, m}, f_{r}=\left\{\left[Y_{r}\right]^{q}-q Y_{r}\right\}$, with $Y_{r}$ being value of previous iterate $Y$ at $x_{r}=r h, \Sigma \alpha_{r, m}$ as in [12], and $p>-1$.

Similarly, in the case of the iterates (10), collecting all $h^{2+p}$ terms on the left-hand side gives
$y_{r+1}-\left\{2+q v_{r}(h)\left[Y_{r}\right]^{q-1}\right\} y_{r}+y_{r-1}=v_{r}(h) g_{r}+O\left(h^{3+p}\right) \quad(1 \leqslant r \leqslant N-1)$
where $g_{r}=(1-q)\left[Y_{r}\right]^{q}$, with $Y_{r}$ being value of previous iterate $Y$ at $x_{r}=r h$, and $v_{r}(h)$, $\Sigma \alpha_{r, m}$ as defined in (13) and (12). For $p>-1$ we have $O\left(h^{2}\right)$ convergence for schemes (13) and (14).

All the discretization schemes have the form

$$
A_{n+1} Y_{n+1}=B_{n} \quad n=0,1,2, \ldots
$$

where $Y_{n+1}$, an $N-1$ column vector, is the approximation to the $(n+1)$ th iterate, $A_{n+1}$ is a tridiagonal matrix of order $N-1$, and $B_{n}$ is an $N-1$ column vector containing the boundary conditions and data relating to the $n$th iterate. Specifically, each matrix $A$ has a constant value 1 in both the sub- and the super-diagonal and the diagonal element $a_{r}$ of $A_{n+1}$ for $1 \leqslant r \leqslant N-1$ is given by

$$
\begin{equation*}
a_{r}=-\left(2+q h^{2+p} r^{p} \sum \alpha_{r, m}\right) \tag{15}
\end{equation*}
$$

for iterations (9) with $p>-1, q>1$.
for iterations (10) with $p>-1, q>1$, where $Y$ is the previous iterate. The elements $b_{r} \quad(1 \leqslant r \leqslant N-1)$ in the column vector $B_{n}$ are given by $\left[\left\{b_{r}\right\}\right]^{T}=$ $[-1,0,0, \ldots, 0,0]^{T}+\left[\left\{\beta_{r}\right\}\right]^{T}$, with:

$$
\begin{equation*}
\beta_{r}=\left(h^{2+p} r^{p} \sum \alpha_{r, m}\right) f_{r} \tag{17}
\end{equation*}
$$

for iterations (9) with $p>-1$ and $q>1$, where $f_{r}=\left\{\left[Y_{r}\right]^{q}-q Y_{r}\right\}$, with $Y$ being the previous iterate \{initially $Y_{r} \equiv 0$ for increasing or $Y_{r}=\left(1-x_{r}\right)=(1-r h)$ for a decreasing sequence $\}$.

$$
\begin{equation*}
\beta_{r}=\left(h^{2+p} r^{p} \sum \alpha_{r, m}\right) g_{r} \tag{18}
\end{equation*}
$$

for iterations (10) with $p>-1$ and $q>1$, where $g_{r}=(1-q)\left[Y_{r}\right]^{q}$, with $Y$ being the previous iterate \{initially $Y_{r}=\left(1-x_{r}\right)=(1-r h)$ giving a decreasing sequence\}.

A tridiagonal routine is used to solve $A_{n+1} Y_{n+1}=B_{n}, n=0,1 \ldots$ Computations for a number of problems are presented in [17], and comparisons are made with previous methods. The results show high accuracy with a small amount of computer effort. In conclusion, the procedure is demonstrated fully for the ionized atom Thomas-Fermi boundary value problem (problem (11) with $p=-\frac{1}{2}$ and $q=\frac{3}{2}$ ).

We discuss the ionized atom Thomas-Fermi problem in detail:

$$
\begin{array}{lll}
y^{\prime \prime}(x)=x^{-1 / 2} y^{3 / 2}(x) & 0<x<1 \\
y(0)=1 & y(1)=0 . & \tag{19}
\end{array}
$$

The approximating sequences for this problem consist of the linear boundary value problems

$$
\begin{align*}
& y_{n+1}^{\prime \prime}(x)-\frac{3}{2} x^{-1 / 2} y_{n+1}(x)=x^{-1 / 2}\left\{\left[y_{n}(x)\right]^{3 / 2}-\frac{3}{2} y_{n}(x)\right\} \\
& y_{n+1}(0)=1 \quad y_{n+1}(1)=0 \tag{20a}
\end{align*}
$$

on using (9), and

$$
\begin{align*}
& y_{n+1}^{\prime \prime}(x)-\frac{3}{2} x^{-1 / 2}\left[y_{n}(x)\right]^{1 / 2} y_{n+1}(x)=-\frac{1}{2} x^{-1 / 2}\left[y_{n}(x)\right]^{3 / 2}  \tag{20b}\\
& y_{n+1}(0)=1
\end{align*} \quad y_{n+1}(1)=0
$$

on using (10). The sequence $\left\{y_{n+1}\right\}, n \geqslant 0$, in (20a) converges monotonically from $y_{0}=0$, or from $y_{0}=1-x$, to the solution $y(x)$ of the Thomas-Fermi problem (19). The sequence $\left\{y_{n+1}\right\}$ in (20b) converges downwards from $y_{0}=1-x$ to the solution $y(x)$ of problem (19). The next step is to obtain finite difference approximations for the equations (20a) and (20b).

Discretizing the scheme (20a) gives, as in (13):

$$
\begin{equation*}
y_{r+1}+a_{r} y_{r}+y_{r-1}=v_{r} f_{r}+O\left(h^{5 / 2}\right) \tag{21}
\end{equation*}
$$

for $1 \leqslant r \leqslant N-1$, with $y_{0}=1, y_{N}=0$ where

$$
\begin{equation*}
a_{r}=-2\left\{1+h^{3 / 2}\left[(r+1)^{3 / 2}+(r-1)^{3 / 2}-2 r^{3 / 2}\right]\right\} \tag{21a}
\end{equation*}
$$

from (12), (15),

$$
\begin{equation*}
v_{r}=\frac{4}{3} h^{3 / 2}\left[(r+1)^{3 / 2}+(r-1)^{3 / 2}-2 r^{3 / 2}\right] \tag{21b}
\end{equation*}
$$

and

$$
\begin{equation*}
\left.f_{r}=\left[Y_{r}\right]^{3 / 2}-\frac{3}{2} Y_{r}\right\} \tag{21c}
\end{equation*}
$$

with $Y$ being the previous iterate. Hence we first solve the tridiagonal scheme $A Y_{\mathrm{t}}=B_{0}$, where $A$ is a fixed tridiagonal matrix with sub and super diagonal elements equal to 1 and $r$ th $(1 \leqslant r \leqslant N-1)$ diagonal element $a_{r}$ given by (21a). In the scheme $A Y_{1}=B_{0}$ the column

$$
\begin{equation*}
B_{0}=\left[v_{1} f_{1}-1, v_{2} f_{2}, \ldots, v_{N-1} f_{N-1}\right]^{T} \tag{22}
\end{equation*}
$$

with $v_{r}$ given by (21b) and $f_{r}$ by (21c). If $Y$ in (21c) is taken to be $Y=[0,0,0, \ldots, 0,0]^{T}$, then the solution $Y_{1}$ of (22) is the first (discretized) lower Picard iterate for problem (19). This iterate is given in table $1 a$ for several discretizations $h=1 / N$. However, if $Y$ in (21c) is taken to be

$$
\begin{equation*}
Y=[(1-h),(1-2 h), \ldots,(1-r h), \ldots,(1-(N-1) h)]^{T} \tag{23}
\end{equation*}
$$

Table 1a. First Picard lower bounds $y_{2}(x)$ for solution of (19). Lower bound $y_{2}(x)$ is the extrapolated limit of $y_{h}(x)$, using (27) $y_{h}(x)$ is solution of discretized first lower Picard iterate (22) $h=1 / N=1 / 1600, x=x_{r}=r h$ for $0 \leqslant r \leqslant N . D_{h}=y_{2 h}-y_{h}, D_{2 h}=y_{4 h}-y_{2 h}$ actual numerical values $=$ table entries $\times 10^{-9}$.

|  | $y_{h}(x)$ <br> $N=1600$ | $D_{h}$ <br> $(1)$ | $y_{2 h}(x)$ <br> $N=800$ | $D_{2 h}$ <br> $(2)$ | $y_{4 h}(x)$ <br> $N=400$ | $y_{8 h}(x)$ <br> $N=200$ | $x$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $y_{1}(x)$ |  |  |  |  |  |  |  |
| 816341088 | 816341161 | 219 | 816341380 | 862 | 816342242 | 816345597 | 0.1 |
| 676635195 | 676635271 | 227 | 676635498 | 895 | 676636393 | 676639899 | 0.2 |
| 560264866 | 560264937 | 211 | 560265148 | 834 | 560265982 | 560269256 | 0.3 |
| 459468617 | 459468680 | 187 | 459468867 | 739 | 459469606 | 459472510 | 0.4 |
| 369682481 | 369682534 | 159 | 369682693 | 628 | 369683321 | 369685793 | 0.5 |
| 287802887 | 287802930 | 129 | 287803059 | 510 | 287803569 | 287805576 | 0.6 |
| 211536747 | 211536780 | 98 | 211536878 | 387 | 211537265 | 211538790 | 0.7 |
| 139089613 | 139089635 | 66 | 139089701 | 261 | 139089962 | 139090992 | 0.8 |
| 068993124 | 068993135 | 34 | 068993169 | 132 | 068993301 | 068993823 | 0.9 |

then the solution $Y_{1}$ of (22) is the first (discretized) upper Picard iterate for problem (19). This iterate is given in table $1 b$ for several discretizations $h=1 / N$.

The next step is to solve $A Y_{2}=B_{1}$, where $B_{1}$ is defined as for $B_{0}$ but with $f_{r}$ now given in terms of the iterate $Y_{1}$ (i.e. $Y=Y_{1}$ ). This enables a sequence of iterates $Y_{1}$, $Y_{2}, \ldots$ to be constructed which converges to the solution of the discretized problem (19) at the grid points $x_{r}=r h, 1 \leqslant r \leqslant N-1$. The convergence rate is linear.

Finally, we describe the discretization of the quadratic scheme (20b). This gives, from (14),

$$
\begin{equation*}
y_{r+1}+a_{r} y_{r}+y_{r-1}=v_{r} g_{r}+O\left(h^{5 / 2}\right) \tag{24a}
\end{equation*}
$$

for $1 \leqslant r \leqslant N-1$, with $y_{0}=1$ and $y_{N}=0$, where

$$
\begin{equation*}
a_{r}=-2\left\{1+h^{3 / 2}\left[(r+1)^{3 / 2}+(r-1)^{3 / 2}-2 r^{3 / 2}\right]\left[Y_{r}\right]^{1 / 2}\right\} \tag{24b}
\end{equation*}
$$

$v_{r}$ is given in (21b), and

$$
\begin{equation*}
g_{r}=-\frac{1}{2}\left[Y_{r}\right]^{3 / 2} \tag{24c}
\end{equation*}
$$

with $Y$ being the previous iterate.
Table 1b. First Picard upper bounds $y^{1}(x)$ for solution of (19). Upper bound $y^{\prime}(x)$ is the extrapolated limit of $y_{h}(x)$, using (27) $y_{h}(x)$ is solution of discretized first upper Picard iterate (22) $h=1 / N=1 / 1600, x=x_{t}=r h$ for $0 \leqslant r \leqslant N . D_{h}=y_{2 h}-y_{h}, D_{2 h}=y_{A h}-y_{2 h}$ actual numerical values $=$ table entries $\times 10^{-9}$.

| $y^{1}(x)$ | $y_{h}(x)$ <br> $N=1600$ | $D_{h}$ <br> $(1)$ | $y_{2 h}(x)$ <br> $N=800$ | $D_{2 h}$ <br> $(2)$ | $y_{4 h}(x)$ <br> $N=400$ | $y_{8 h}(x)$ <br> $N=200$ | $x$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 850718983 | 850719042 | 175 | 850719217 | 690 | 850719907 | 850722597 | 0.1 |
| 729624593 | 729624655 | 184 | 729624839 | 725 | 729625564 | 729628409 | 0.2 |
| 626610569 | 622610627 | 173 | 622610800 | 684 | 622611484 | 622614172 | 0.3 |
| 524332582 | 524332634 | 155 | 524332789 | 613 | 524333402 | 524335814 | 0.4 |
| 431691062 | 431691106 | 133 | 431691239 | 528 | 431691767 | 431693846 | 0.5 |
| 342650317 | 342650354 | 110 | 342650464 | 435 | 342650899 | 342652612 | 0.6 |
| 255798924 | 255798952 | 84 | 255799036 | 336 | 255799372 | 255800697 | 0.7 |
| 170144790 | 170144809 | 58 | 170144867 | 232 | 170145099 | 170146012 | 0.8 |
| 085012173 | 085012183 | 30 | 085012213 | 121 | 085012334 | 085012811 | 0.9 |

Hence we first solve the tridiagonal scheme

$$
\begin{equation*}
A_{1} Y_{1}=B_{0} \tag{25}
\end{equation*}
$$

where $A_{1}$ has the same form as the matrix $A$ in (22) but with the diagonal elements $a_{r}$, as given by ( $24 a$ ), iterate dependent (on $Y$ ). The column $B_{0}=\left[v_{1} g_{1}-1\right.$, $\left.v_{2} g_{2}, \ldots, v_{N-1} g_{N-1}\right]^{T}$, with $v_{r}$ given by (21b) and $g_{r}$ by (24c), where $Y$ is as in (23a). The solution $Y_{1}$ is the first (discretized) upper Newton iterate for the problem (19). This iterate is given in table $1 c$ for several discretizations $h=1 / N$. We next solve $A_{2} Y_{2}=B_{1}$, where $A_{2}$ has diagonal elements given by ( $24 a$ ) with $Y=Y_{1}$, the previously found iterate, and the column $B_{1}$ is the same as $B_{0}$ but with $g_{r}$ now in terms of the previous iterate $Y=Y_{1}$. Then the quadratically convergent sequence ( $20 b$ ) discretizes as $A_{n+1} Y_{n+1}=B_{n}, n=0,1, \ldots$, producing a sequence $\left\{Y_{n+1}\right\}$ converging to the solution of the discretized problem (19) at the grid points $x_{r}=r h(1 \leqslant r \leqslant N-1)$.

Table 1c. First Newton upper bounds $y^{1}(x)$ for solution of (19). Upper bound $\underline{y}^{1}(x)$ is the extrapolated limit of $y_{h}(x)$, using (27) $y_{h}(x)$ is solution of discretized first upper Newton iterate (25) $h=1 / N=1 / 1600, x=x_{r}=r h$ for $0 \leqslant r \leqslant N . D_{h}=y_{2 h}-y_{h}, D_{2 h}=y_{4 h}-y_{2 h}$ actual numerical values $=$ table entries $\times 10^{-9}$.

|  | $y_{h}(x)$ <br> $N=1600$ | $D_{h}$ <br> $(1)$ | $y_{2 h}(x)$ <br> $N=800$ | $D_{2 h}$ <br> $(2)$ | $y_{4 h}(x)$ <br> $N=400$ | $y_{\text {sh }}(x)$ <br> $N=200$ | $x$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $\underline{y}^{\mathrm{I}}(x)$ |  |  |  |  |  |  |  |
| 849621180 | 849621239 | 177 | 849621416 | 694 | 849622110 | 849624817 | 0.1 |
| 727501050 | 727501112 | 186 | 727501298 | 733 | 727502031 | 727504903 | 0.2 |
| 619644832 | 619644890 | 175 | 619645065 | 694 | 619645759 | 619648484 | 0.3 |
| 520800241 | 520800294 | 158 | 520800452 | 625 | 520801077 | 520803534 | 0.4 |
| 427928975 | 427929021 | 137 | 427929158 | 540 | 427929698 | 427931825 | 0.5 |
| 339023757 | 339023795 | 113 | 339023908 | 446 | 339024354 | 339026113 | 0.6 |
| 25266904 | 252669033 | 87 | 25266120 | 346 | 25669466 | 25260828 | 0.7 |
| 167836520 | 167836540 | 60 | 167836600 | 238 | 167836838 | 167837777 | 0.8 |
| 083782101 | 083782111 | 31 | 083782142 | 124 | 083782266 | 083782753 | 0.9 |

The discretized problems (21) and (24) were solved for several mesh widths $h$ between $h=0.5 \times 10^{-2}$ and $h=0.625 \times 10^{-3}$ and the difference columns (1) and (2) obtained as indicated in the tables. These difference columns were used with either of the 'deferred approach to the limit' formulae:

$$
\begin{align*}
& s=\frac{d}{3}+p  \tag{26}\\
& s=\frac{19 d}{45}-\frac{e}{45}+p \tag{27}
\end{align*}
$$

where $h$ is the uniform mesh width, $s$ is the solution using the 'deferred correction' formula, $p$ is the approximate solution $y_{h}$ with mesh size $h$, and $d, e$ are the differences $y_{h}-y_{2 h}, y_{2 h}-y_{4 h}$, respectively. This produces the columns for $s=y_{1}, y^{1}, \underline{y}^{1}$, and $\underline{y}$ shown in tables 1 and 2. For an $O\left(h^{2}\right)$ accurate discretization process, formula (27) is the more accurate. The $O\left(h^{2}\right)$ accuracy is demonstrated by the difference columns (1), (2) in the tables being in the ratio $1: 4$. In the tables, $y_{1}(x)$ and $y^{1}(x)$ are the first lower and upper bounds for the solution of the Thomas-Fermi problem (19), obtained by using (20a) with $y_{0}(x)=0$ and $y_{0}(x)=1-x$, respectively. Also, $\underline{y}^{\prime}(x)$ is the first

Table 2. Accurate numerical solution of (19) by iteration. Solution $\underline{y}(x)$ is the extrapolated limit of $y_{h}(x)$, using (27) $y_{h}(x)$ is iterated solution of either scheme (21) or scheme (24) $h=1 / N=1 / 1600, x=x_{r}=r h$ for $0 \leqslant r \leqslant N . D_{h}=y_{2 h}-y_{h}, D_{2 h}=y_{4 h}-y_{2 h}$ actual numerical values $=$ table entries $\times 10^{-9}$.

|  | $y_{h}(x)$ <br> $N=1600$ | $D_{h}$ <br> $(1)$ | $y_{2 h}(x)$ <br> $N=800$ | $D_{2 h}$ <br> $(2)$ | $y_{4 h}(x)$ <br> $N=400$ | $y_{8 h}(x)$ <br> $N=200$ | $x$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $\underline{y}(x)$ | 849474441 | 177 | 849474618 | 695 | 849475313 | 849478024 | 0.1 |
| 849474382 | 727231915 | 187 | 727232102 | 735 | 727232837 | 727235717 | 0.2 |
| 727231852 | 619294575 | 176 | 619294751 | 697 | 619295448 | 619298186 | 0.3 |
| 619294515 | 520414560 | 158 | 520414718 | 629 | 520415347 | 520417819 | 0.4 |
| 520414506 | 527550063 | 138 | 427550201 | 544 | 427550745 | 427552888 | 0.5 |
| 427550017 | 42750 |  |  |  |  |  |  |
| 338686150 | 338686188 | 114 | 338686302 | 450 | 338686752 | 338688526 | 0.6 |
| 252398194 | 252398223 | 88 | 252398311 | 349 | 252398660 | 252400035 | 0.7 |
| 167649022 | 167649042 | 61 | 167649103 | 240 | 167649343 | 167650291 | 0.8 |
| 083686767 | 083686778 | 32 | 083686810 | 125 | 083686935 | 083687427 | 0.9 |

upper bound obtained using (20b) with $y_{0}(x)=1-x$. Applying (20a) and (20b) iteratively, the iterates $y_{8}(x), y^{7}(x)$ and $y^{3}(x)$ were found to be identical to nine decimal places for each discretization $h=1 / N$ used, and are given as discretized solutions $y_{h}(x)$ for problem (19) in table 2. Applying the formula (26) or (27) gives the column for $s=\underline{y}(x)$, the approximate solution of (19) to nine decimal places given in table 2.

The tabulated results agree with those in [4]. These are given without the decimal point for clarity, the actual values being multiplied by $10^{-9}$.

In conclusion, when the interval length $a$ in (6) is larger than 20, at least 100 iterations are required for the scheme (9) but only 6 for the scheme (10). In these cases, Chan's method [4] is expensive. The discretization schemes were realized using double precision on an IBM PC ( 640 K ) with maths co-processor. The method can be used with other boundary conditions and on problems where there is a degeneracy of class $D_{P}^{2}, 0<P<1$, on the boundary. Finally, other more general physical problems may often reduce to a problem of the form (11).

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